



seit 1558

One-Class Classification with Gaussian Processes

Michael Kemmler, Erik Rodner, and Joachim Denzler

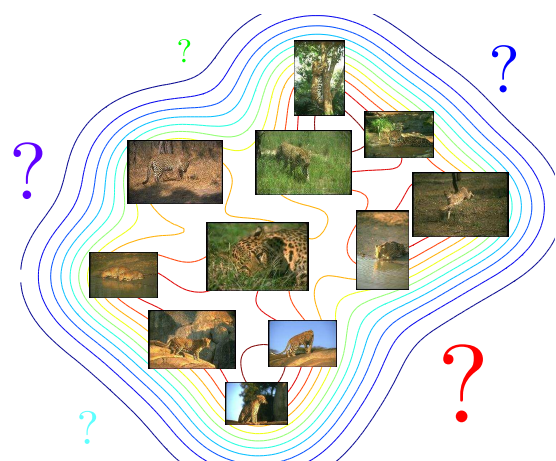
Chair for Computer Vision
Friedrich Schiller University of Jena

{michael.kemmler, erik.rodner, joachim.denzler}@uni-jena.de
www.inf-cv.uni-jena.de

The work was funded by the German Excellence Initiative "MikroPlex"



One-Class Classification



IN MANY TASKS, ONLY POSITIVE TRAINING EXAMPLES ARE AVAILABLE!

This problem is known as

- One-Class Classification
- Outlier and Failure Detection
- Novelty Detection

Gaussian Processes Regression

- non-parametric regression: $y = f(\mathbf{x}) + \varepsilon$, given data (\mathbf{X}, \mathbf{y})
- assumptions: $\mathbf{f} = f(\mathbf{X}) \sim \mathcal{N}(\mathbf{0}, \kappa(\mathbf{X}, \mathbf{X}))$, $\mathbf{y} \sim \mathcal{N}(\mathbf{f}, \sigma_n^2 \mathbf{I})$
- Inference [1] for unknown points \mathbf{x}_* : $p(f_* | \mathbf{X}, \mathbf{y}, \mathbf{x}_*) \sim \mathcal{N}(\mu_*, \sigma_*^2)$, where

$$\mu_* = \mathbf{k}_*^T (\mathbf{K} + \sigma_n^2 \mathbf{I})^{-1} \mathbf{y}$$

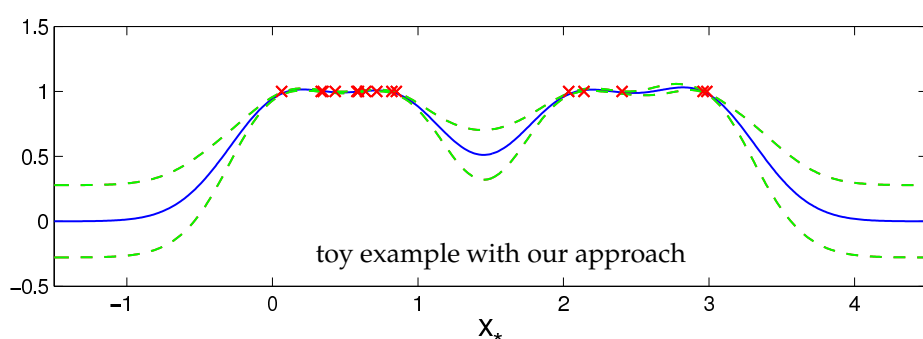
$$\sigma_*^2 = k_{**} - \mathbf{k}_*^T (\mathbf{K} + \sigma_n^2 \mathbf{I})^{-1} \mathbf{k}_*$$

- with shorthands $\mathbf{K} = \kappa(\mathbf{X}, \mathbf{X})$, $\mathbf{k}_* = \kappa(\mathbf{X}, \mathbf{x}_*)$ and $k_{**} = \kappa(\mathbf{x}_*, \mathbf{x}_*)$
- using some kernel κ , e.g. squared exponential kernel:

$$\kappa_{SE}(\mathbf{x}, \mathbf{x}') = \nu_0^2 \exp\left(-\frac{1}{2\nu_1^2} \|\mathbf{x} - \mathbf{x}'\|^2\right)$$

One-Class Classification with Gaussian Processes

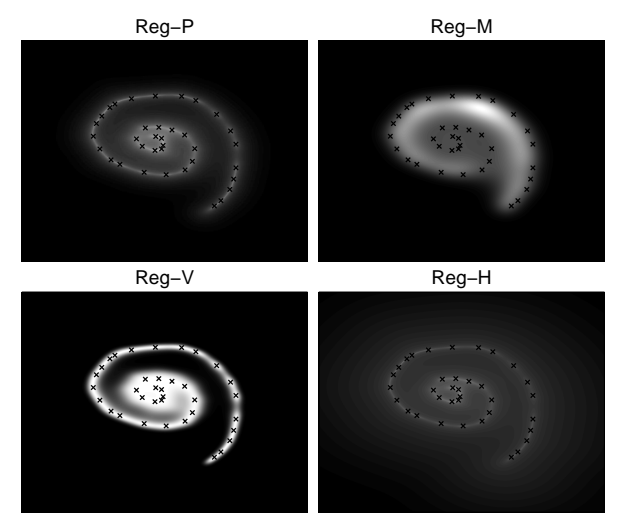
- **Our contribution:** new OCC methods using GP priors
- Fitting the data to labels $y = 1$ and using a **zero-mean** GP prior favours functions suitable for OCC



- various OCC measures can be derived from the predictive distribution

| | |
|----------------------|--|
| 1. Probability (P) | $p(y_* = 1 \mathbf{X}, \mathbf{y}, \mathbf{x}_*)$ |
| 2. Mean (M) | $\mu_* = \mathcal{E}(y_* \mathbf{X}, \mathbf{y}, \mathbf{x}_*)$ |
| 3. neg. Variance (V) | $-\sigma_*^2 = -\mathcal{V}(y_* \mathbf{X}, \mathbf{y}, \mathbf{x}_*)$ |
| 4. Heuristic (H) | $\mu_* \cdot \sigma_*^{-1}$ |

- use OCC measures as class membership scores



Visualization of some methods on a spiral example

Visual Object Recognition

Task 1: separate image categories from background

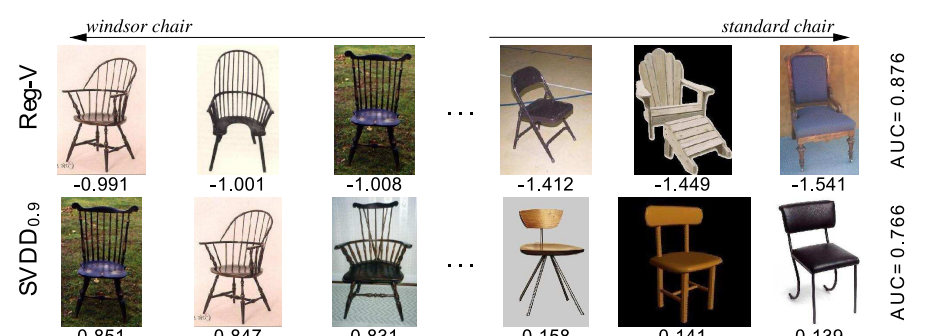
- utilize image kernels: PHoG [2] and Color [3] spatial pyramids
- compare against SVDD [4] with outlier fraction $\nu \in \{0.1, 0.2, \dots, 0.9\}$
- avg. AUCs over all class-background problems (15 training samples):

| Caltech 101 | Reg-P | Reg-M | Reg-V | Reg-H | SVDD _{0.5} | SVDD _{0.9} |
|-------------|-------|-------|--------------|-------|---------------------|---------------------|
| PHoG | 0.696 | 0.693 | 0.692 | 0.696 | 0.690 | 0.685 |
| Color | 0.761 | 0.736 | 0.766 | 0.755 | 0.739 | 0.746 |

- additional experiments show: GP regression outperforms GP classification

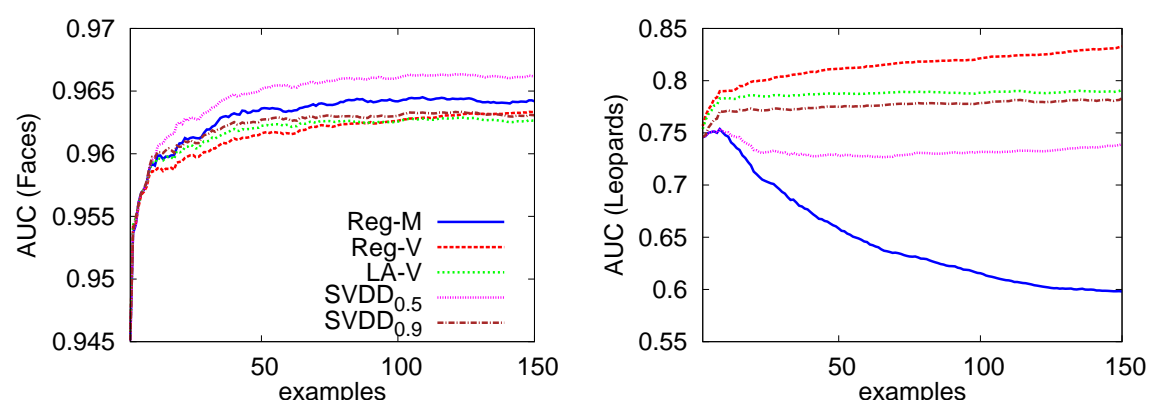
Task 2: separate between different sub-categories

- e.g. class *windsor chair* versus *chair* (30 training samples)



Impact of training size (Task 1)

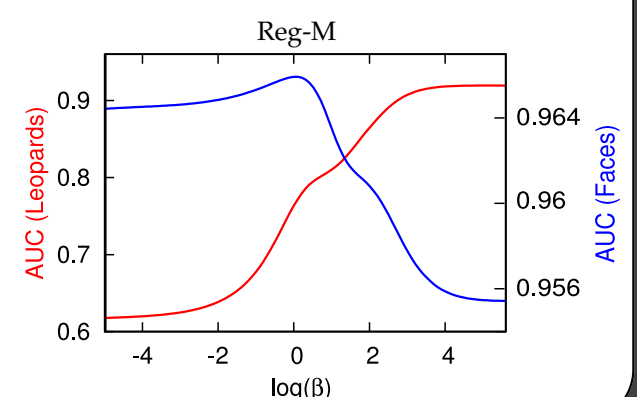
- performance can decrease with more training examples (Reg-M, SVDD_{0.5})
- potential problem: fixed (implicit) scale parameter of the kernel



Introduction of an Explicit Scale Parameter

- we use a generalized rbf kernel [5]: $\kappa_\beta(\mathbf{x}, \mathbf{x}') = \exp(-\beta d_\kappa^2(\mathbf{x}, \mathbf{x}'))$, where $d_\kappa^2(\mathbf{x}, \mathbf{x}') = \kappa(\mathbf{x}, \mathbf{x}) - 2\kappa(\mathbf{x}, \mathbf{x}') + \kappa(\mathbf{x}', \mathbf{x}')$

- performance of Reg-M highly depends on β
- optimal β is task specific
- tuning the scale parameter leads to significant performance benefits



Conclusion

- investigates non-parametric OCC scores via Gaussian processes
- general method is easy to implement
- significantly better results compared to SVDD
- suitable for object recognition using image kernels
- depends on scale parameter (hard to obtain)



References

- [1] Rasmussen, C.E., Williams, C.K.I.: Gaussian Processes for Machine Learning (Adaptive Computation and Machine Learning). The MIT Press (2005)
- [2] Bosch, A., Zisserman, A., Munoz, X.: Representing shape with a spatial pyramid kernel. In: Proceedings of the 6th ACM international conference on Image and video retrieval. (2007) 401–408
- [3] van de Sande, K.E.A., Gevers, T., Snoek, C.G.M.: Evaluating color descriptors for object and scene recognition. IEEE Trans. Pattern Anal. Mach. Intell. (2010)
- [4] Tax, D.M.J., Duin, R.P.W.: Support vector data description. Mach. Learn. 54 (2004) 45–66
- [5] Vedaldi, A., Soatto, S.: Relaxed matching kernels for object recognition. In: Proceedings of the IEEE Conf. on Computer Vision and Pattern Recognition. (2008)