



since 1558

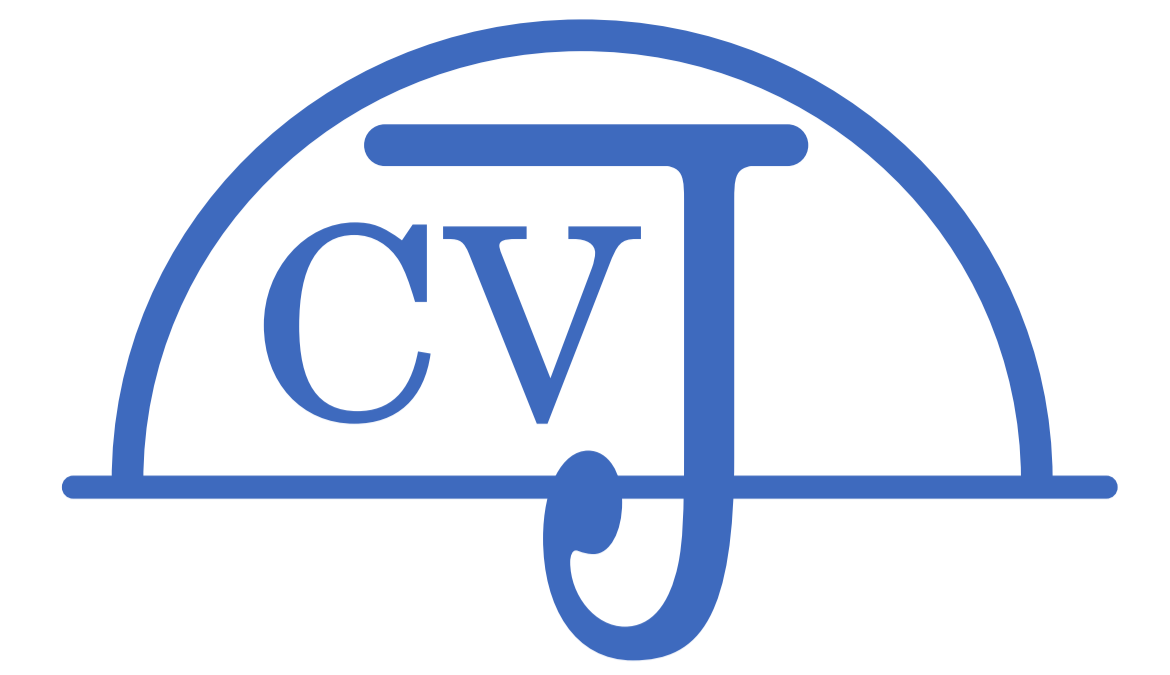
Divergence-Based One-Class Classification Using Gaussian Processes

Paul Bodesheim, Erik Rodner, Alexander Freytag, Joachim Denzler

Computer Vision Group, Friedrich Schiller University Jena, Germany

{Paul.Bodesheim,Erik.Rodner,Alexander.Freytag,Joachim.Denzler}@uni-jena.de

<http://www.inf-cv.uni-jena.de/>



Friedrich Schiller University Jena

Computer Vision Group

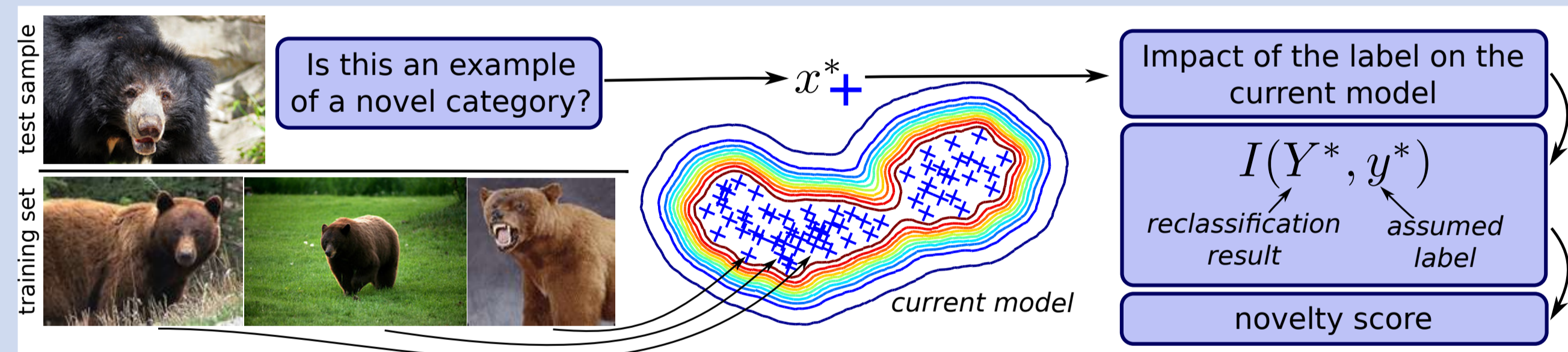
One-class classification (OCC)

- Given: a set of only positive training samples of a single class
- Goal: estimate a soft membership score for a test sample
- Why?: negative data is difficult to model or is hard to obtain

Aim of this work

Shed light on one-class classification from a completely different theoretical perspective

- Measure how strongly a new test sample would influence the current model if it was used for training
- Estimation of model change by comparing reclassification results
- Probabilistic framework based on information theory



Gaussian process regression [RW06]

- Continuous outputs y_c are assumed to be generated according to:

$$y_c(\mathbf{x}) = f(\mathbf{x}) + \varepsilon \quad (f \dots \text{latent function, } \varepsilon \dots \text{noise term})$$

- Output values of unknown samples \mathbf{x}^* are predicted in a probabilistic fashion by marginalising over latent functions f

- Assumptions:

1 Latent functions f are drawn from a Gaussian process prior with mean function being zero and covariance function $\kappa(\cdot, \cdot)$

2 The noise term is normally distributed: $\varepsilon \sim \mathcal{N}(0, \sigma_n^2)$.

⇒ Predictive output value y_c^* for a new sample \mathbf{x}^* given the data \mathbf{D}^* is normally distributed as well: $y_c^* | \mathbf{D}^* \sim \mathcal{N}(\mu_*, \sigma_*^2)$

$$\mu_* = \mathbf{k}_*^T (\mathbf{K} + \sigma_n^2 \mathbf{I})^{-1} \mathbf{1}$$

$$\sigma_*^2 = \mathbf{k}_{**} - \mathbf{k}_*^T (\mathbf{K} + \sigma_n^2 \mathbf{I})^{-1} \mathbf{k}_* + \sigma_n^2$$

- Label regression for OCC [KRD10]: GP-Mean, GP-Var, GP-Pred

Divergence-based one-class classification

- Assumed label of test sample: $y^* \in \{-1, 1\}$
- Reclassification result of test sample: $Y^* \in \{-1, 1\}$
- Influence of test sample on current model via **conditional mutual information**:

$$I(Y^*, y^* | \mathbf{D}^*) = H(Y^* | \mathbf{D}^*) - H(Y^* | y^*, \mathbf{D}^*)$$

H ... Shannon entropy, $\mathbf{D}^* = (\mathbf{X}, \mathbf{y}, \mathbf{x}^*)$, \mathbf{X} ... training samples, $\mathbf{y} = 1$... labels, \mathbf{x}^* ... test sample

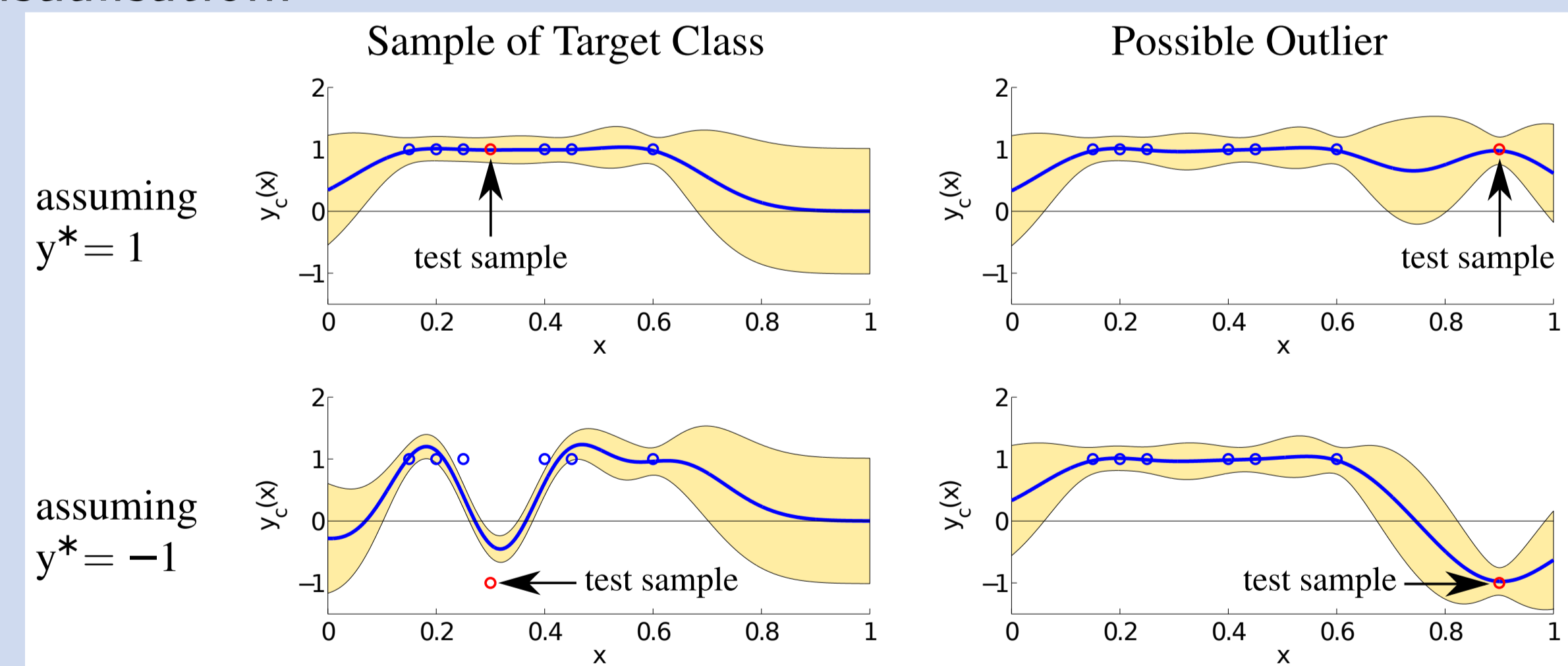
- Conditional mutual information turns out to be equal to the **Jensen-Shannon (JS) divergence**:

$$I(Y^*, y^* | \mathbf{D}^*) = D_{\text{JS}}^{\pi}(\mathbf{p}_1 || \mathbf{p}_{-1}) = \pi \cdot D_{\text{KL}}(\mathbf{p}_1 || \mathbf{m}) + (1 - \pi) \cdot D_{\text{KL}}(\mathbf{p}_{-1} || \mathbf{m})$$

$D_{\text{KL}}(\cdot || \cdot)$... Kullback-Leibler divergence, $\mathbf{m} = \pi \cdot \mathbf{p}_1 + (1 - \pi) \cdot \mathbf{p}_{-1}$... mixture of

$\mathbf{p}_1 = p(Y^* | y^* = 1, \mathbf{D}^*)$ and $\mathbf{p}_{-1} = p(Y^* | y^* = -1, \mathbf{D}^*)$ with prior $\pi = p(y^* = 1 | \mathbf{D}^*)$

- Visualisation:



Gaussian process probabilities for divergence-based OCC

- Prior probabilities (new novelty measure **GP-Prob**):

$$\pi = p(y^* = 1 | \mathbf{D}^*) = p(y_c^* > 0 | \mathbf{D}^*) = \frac{1}{2} - \frac{1}{2} \operatorname{erf}\left(\frac{-\mu_*}{\sqrt{2\sigma_*^2}}\right)$$

- Conditional probabilities from reclassification:

$$p(Y^* = 1 | y^*, \mathbf{D}^*) = p(y_c^* > 0 | y^*, \mathbf{D}^*)$$

$$p(Y^* = -1 | y^*, \mathbf{D}^*) = 1 - p(y_c^* > 0 | y^*, \mathbf{D}^*)$$

- Balancing in reclassification via different noise levels is optional

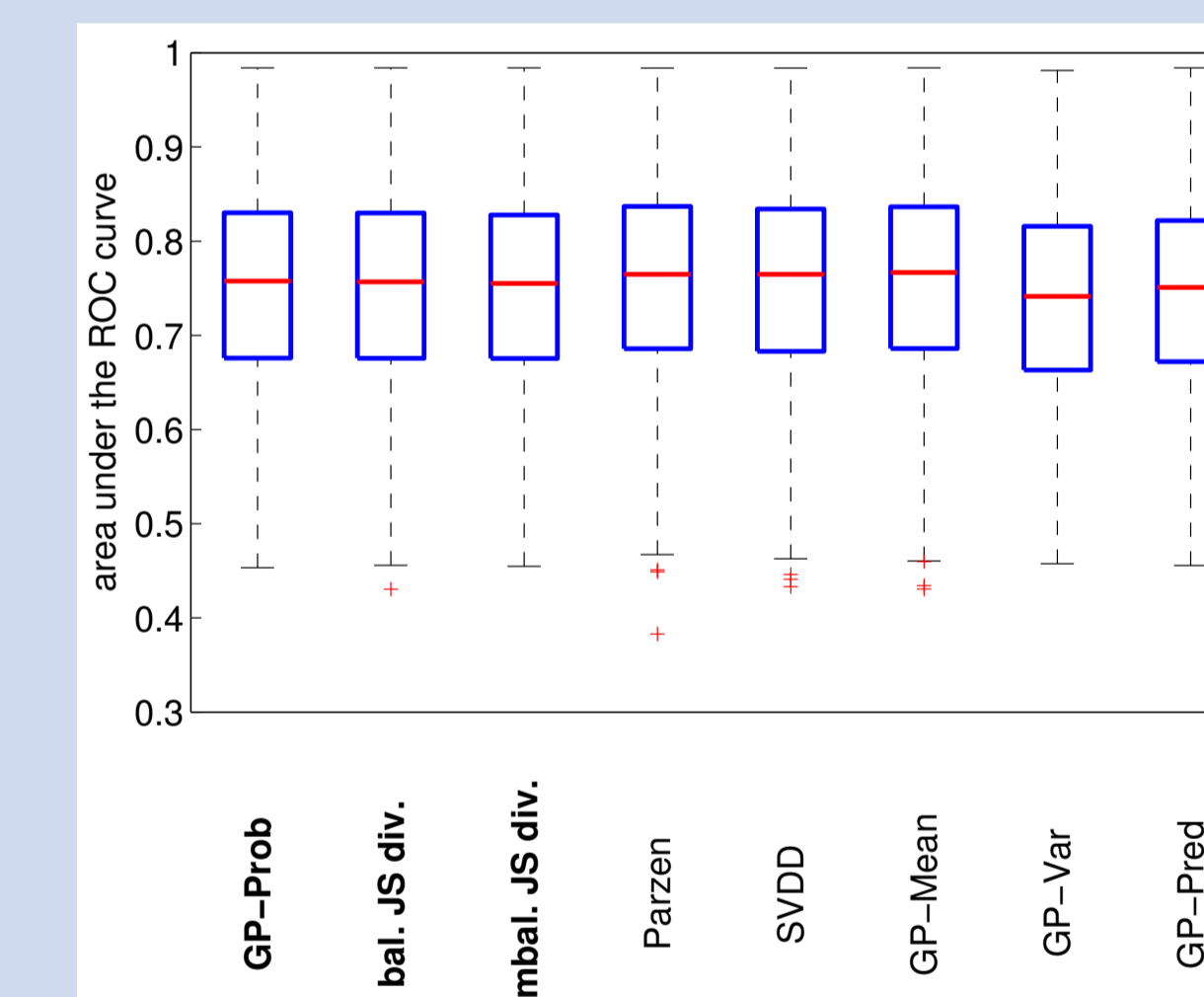
⇒ **balanced or imbalanced JS divergence**

Experimental Results

- UCI datasets (best three results of each task are underlined)

| OCC method | Median AUC of target class | | | |
|-----------------------|----------------------------|-----------------------|--------------------|--------------------|
| | <i>Iris-Versicolour</i> | <i>Iris-Virginica</i> | <i>Sonar-Rocks</i> | <i>Sonar-Mines</i> |
| GP-Prob | <u>0.981</u> | 0.966 | <u>0.625</u> | <u>0.772</u> |
| bal. JS div. | <u>0.981</u> | 0.967 | <u>0.618</u> | 0.768 |
| imbal. JS div. | <u>0.981</u> | <u>0.968</u> | <u>0.624</u> | <u>0.773</u> |
| Parzen [Bis06] | 0.973 | 0.960 | 0.602 | 0.771 |
| SVDD [TD04] | <u>0.986</u> | <u>0.971</u> | 0.609 | 0.761 |
| GP-Mean [KRD10] | <u>0.983</u> | <u>0.974</u> | 0.613 | 0.756 |
| GP-Var [KRD10] | 0.979 | 0.964 | 0.608 | 0.770 |
| GP-Pred [KRD10] | 0.980 | 0.968 | <u>0.618</u> | <u>0.776</u> |

- ImageNet (Visual Object Recognition)



| OCC method | Median AUC (Std. dev.) |
|-----------------------|------------------------|
| GP-Prob | 0.758 (± 0.103) |
| bal. JS div. | 0.757 (± 0.103) |
| imbal. JS div. | 0.755 (± 0.103) |
| Parzen [Bis06] | 0.765 (± 0.105) |
| SVDD [TD04] | 0.765 (± 0.103) |
| GP-Mean [KRD10] | 0.767 (± 0.103) |
| GP-Var [KRD10] | 0.741 (± 0.104) |
| GP-Pred [KRD10] | 0.751 (± 0.103) |

Conclusions

- New one-class classification framework based on information theory
- Gaussian process probabilities are suitable for this framework
- Results comparable to state-of-the-art

References

- BISHOP, Christopher M.: *Pattern Recognition and Machine Learning (Information Science and Statistics)*. Springer, 2006
- FILIPPONE, Maurizio ; SANGUINETTI, Guido: Information theoretic novelty detection. In: *Pattern Recognition* 43 (2010), Nr. 3, S. 805–814
- KEMMLER, Michael ; RODNER, Erik ; DENZLER, Joachim: One-Class Classification with Gaussian Processes. In: *ACCV*, 2010, S. 489–500
- RASMUSSEN, Carl E. ; WILLIAMS, Christopher K. I.: *Gaussian Processes for Machine Learning*. The MIT Press, 2006
- TAX, David M. J. ; DUIN, Robert P. W.: Support Vector Data Description. In: *Machine Learning* 54 (2004), Nr. 1, S. 45–66